

# Video Blur Detection

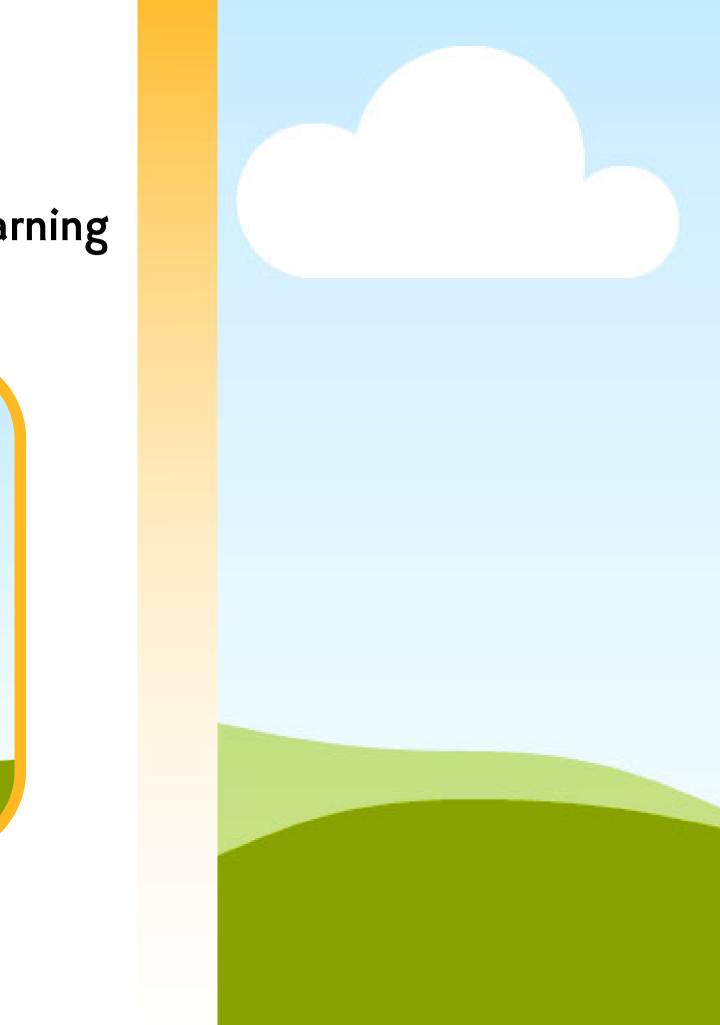
Anurodh Jain Pragya Roy Ronak Dedhiya



## Objective

Domain : Image Processing, Computer vision, Machine Learning

Study various blur detection techniques and provide a comparative performance of the available state-of-the-art methods for classification of blurry versus non-blurry video Measure & compare performance in terms of precision, recall, f-measure, accuracy, execution time showing the effectiveness of Blur detection techniques.



### DataSet

Description

#### • Train Data:

- 18 Scenarios
- 5 videos per scenario (No distortion + 4 distortion type)
- 90 videos
- Test Data:
  - 7 Scenarios
  - 35 videos
- Each video is of 10 sec duration with uniform distortion.

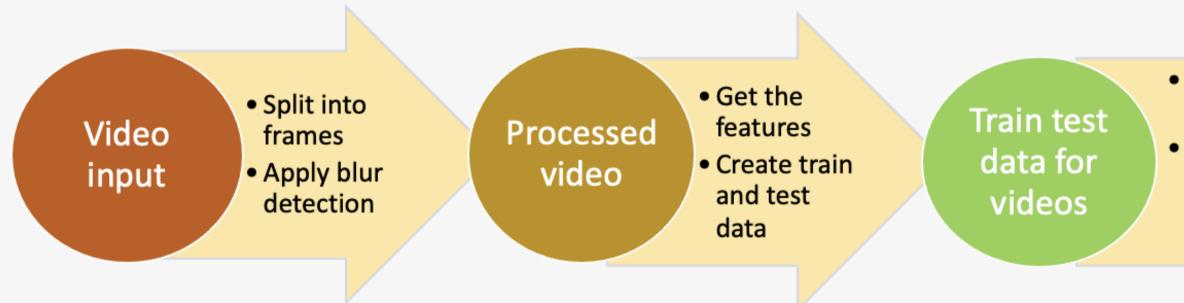


#### Dataset link

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https://vsquad2022.aliqureshi.info/index.html https://www.l2ti.univ-paris13.fr/VSQuad/

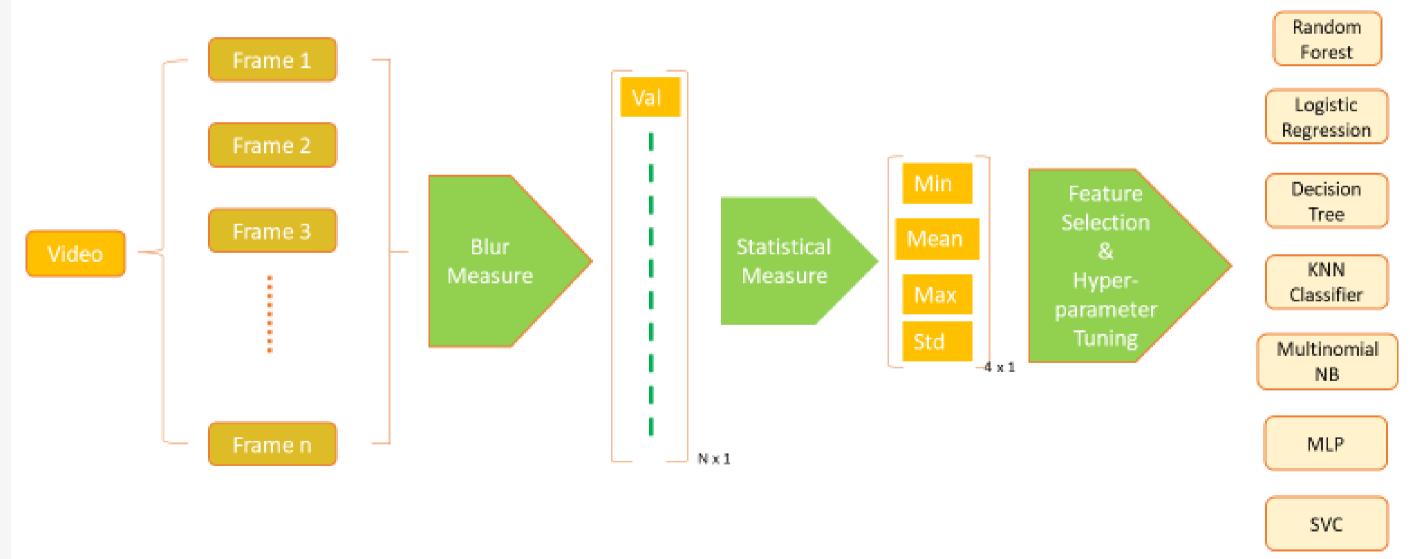
### **Process Flow**



 Create ML Models
Perform Hyper Parameter Tuning

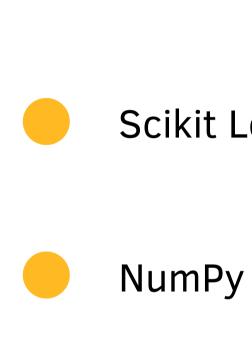
Different Tuned Models Run pipeline on test data and get evaluation metrics

## > Detailed Flow



End to End Video Blur Detection Pipeline

### Tools / Libraries



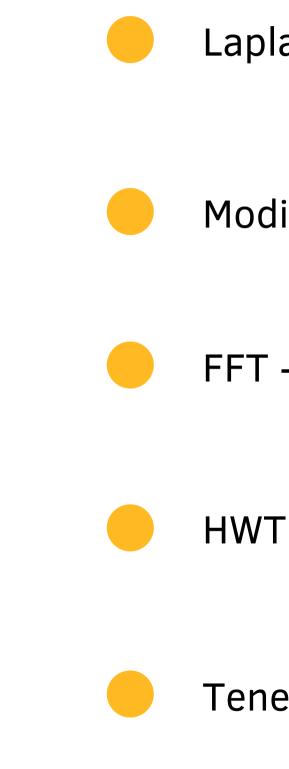


#### Open CV

Scikit Learn

Pandas

Blur Detection Techniques



#### Laplacian

Modified Laplacian

#### FFT - Fast Fourier Transform

#### Tenengrad

## LAPLACIAN OPERATOR (LAP)





Laplace operator of a discrete function is obtained by making difference on the second derivative of Laplace operator in X and Y directions.

Highlights regions of an image containing rapid intensity changes.

H

High variance in intensity – sharp image Low variance in intensity – blurred image

### Features

## **Evaluation Metrics**

Classifer	Features Used	Parameters	Accuracy	Recall	Precision	F1Score
Random Forest	min	Depth=2, Estimator=10	0.767	0.964	0.9	0.931
Logistic Regression	min	C = 0.1, 12, balanced	0.767	0.964	0.9	0.931
Decision Tree	min, mean, std	Balanced, depth=4, min split=3	nced, depth=4, min split=3 0.821		0.928	0.928
KNN Classifier	min,mean,max	$N_{neigbours} = 4$	0.83	0.964	0.93	0.947
Multinomial NB	min,max	alpha = 1	0.696	0.964	0.87	0.915
MLP	mean, std	alpha=5e-3, hidden = (10,10,10)	0.839	0.964	0.93	0.947
SVC(Poly)	mean, std	C=10, balanced, degree = $2$	0.839	0.964	0.93	0.947

Average Laplacian operation time per video : 17 sec

## MODIFIED LAPLACIAN OPERATOR (MLAP)



Compute local measures of the quality of image focus by getting the absolute values of the second derivatives.

### Features

Instead of looking at variance, check for absolute value of filtered image.

Higher the laplacian value (either +ve or -ve), higher the image sharpness

## > Evaluation Metrics

Classifer	Features Used	Parameters	Accuracy	Recall	Precision	F1Score	
Random Forest	min	None, depth=2, estimator=30	0.5	1	0.8	0.889	
Logistic Regression	Regression min,mean,max,std C=0.01, Ba		0.607	0.5	0.875	0.636	
Decision Tree	min	Balanced, depth=2, split=2	0.5	1	0.8	0.889	
KNN	min	Neighbours = 5	0.5	1	0.8	0.889	
Multinomial NB	min	alpha = 10	0.5	1	0.8	0.889	
MLP	min	adam, layer size=10, 0.001	0.5	1	0.8	0.889	
SVC(Poly)	min C=1,None, degr		0.5	1	0.8	0.889	

Average Modified Laplacian operation time per video : **19 sec** 

**Implication**: The modified laplacian has a low accuracy score as compared to Laplacian, indicating that the features are less discriminative

## FAST FOURIER TRNASFORM (FFT)



Algorithm for computing the Discrete Fourier Transform, used to decompose an image into its sine and cosine components.

Transform Image from spatial domain to frequency domain.

calculates the frequencies in the image at different points. higher frequencies - more sharpness lower frequencies - more bluriness

### Features

## > Evaluation Metrics

Classifer	Features Used	Parameters	Accuracy	Recall	Precision	F1Score
Random Forest	min,max	Depth=4, Estimator=30, balanced	0.767	0.964	0.9	0.931
Logistic Regression	min,mean	C= 0.01,Balanced, 12	0.75	0.928	0.896	0.912
Decision Tree	max,std	Balanced, depth=3, min split=2	0.73	0.89	0.89	0.89
KNN	max	Neighbours $= 2$	0.803	0.89	0.925	0.91
Multinomial NB	std	alpha = 1	0.5	1	0.8	0.89
MLP	min,mean,max,std	alpha=0.05, hidden layer=10	0.642	1	0.848	0.918
SVC(Poly)	mean	balanced, degree = $2, C = 1$	0.75	0.928	0.896	0.912

Average FFT operation time per video : 95 sec

## HaarWavelet Transform (HWT)



Classifies an image as blurred or sharp by splitting it into N x N tiles, applying several iterations of the 2D HWT to each tile, and grouping horizontally, vertically, and diagonally connected tiles with pronounced changes into tile clusters.

#### Features



Images with large tile clusters are classified as sharp. Images with small tile clusters are classified as blurred

## **Evaluation Metrics**

Classifer	Features Used	Parameters	Accuracy	Recall	Precision	F1Score
Random Forest	min,max	Depth=2, Estimator=30,None	0.767	0.964	0.9	0.931
Logistic Regression	min	C=1,None, 12	0.75	0.928	0.896	0.912
Decision Tree	max	Balanced, depth=4, min split=4	0.803	0.898	0.925	0.9
KNN	max or mean_std	neighBour = 2	0.75	0.928	0.896	0.912
Multinomial NB	max	alpha = 10	0.5	1	0.8	0.889
MLP	min,max	adam,(10,10), 5e-3	0.767	0.964	0.9	0.931
SVC(poly)	mean,std	Balanced, degree = $3, C = 0.01$	0.857	0.857	0.96	0.905

Average HWT operation time per video : **76 sec** 





### TENENGRAD





Both the horizontal and vertical gradient component when combined, generates the magnitude (measure of change of brightness) for a given pixel

### Features



Sharper images will produce larger gradient magnitudes when compared with blurry images

## **Evaluation Metrics**

Classifer	Features Used	Parameters	Accuracy	Recall	Precision	F1Score
Random Forest	mean,std	balanced, depth=2, estimators = 30	0.75	0.928	0.896	0.912
Logistic Regression	mean,std	balanced, 12, C = 10	0.73	0.89	0.892	0.892
Decision Tree	max	Depth=3, min split=3, None	0.696	0.964	0.87	0.915
KNN	max	neighbours $= 3$	0.696	0.964	0.87	0.915
Multinomial NB	mean,max	alpha = 1	0.57	1	0.823	0.903
MLP	max,std	1e-3, (10,10,10), adam	0.625	0.964	0.843	0.9
SVC(Poly)	max	max Balanced, C = 0.01, Degree = 2		0.892	0.892	0.892

Average Tenangrad operation time per video : 68 sec

### **Summary**

Blur Detection Technique	Classifer	Features Used	Parameters	Accuracy	Recall	Precision	F1Score	Execution Time (sec)
FFT	Random Forest	min,max	Depth=4, Estimator=30, balanced	0.767	0.964	0.9	0.931	95
Laplacian	SVC(Poly)	std	C=10, balanced, degree = $2$	0.839	0.964	0.93	0.947	17
Modified Laplacian	Random Forest	min	None, depth=2, estimator=30	0.5	1	0.8	0.889	19
HWT	MLP	min,max	adam,(10,10), 5e-3	0.767	0.964	0.9	0.931	76
Tenengrad	KNN	max	neighbours $= 3$	0.696	0.964	0.87	0.915	68
FFT + laplacian + modified laplacian	<b>Randome Forest</b>	min	depth =2, estimators = 10, none	0.857	1	0.933	0.9657	131
Laplacian + modified laplacian	Random Forest	Laplacian(max, std), Modified Laplacian(mean)	Depth = 4, estimator = 30	0.857	1	0.933	0.9657	36

#### **Combination of the features provides us the best results**

1Pagaduan, Roxanne A., Ma Christina R. Aragon, and Ruji P. Medina. "iblurdetect: Image blur detection techniques assessment and evaluation study." In Proceedings of the International Conference on Culture Heritage, Education, Sustainable Tourism, and Innovation Technologies-CESIT, pp. 286-291, 2021.

### References

**Project Code:** 

Dataset link:

https://github.com/RonakDedhiya/Video\_Blur\_Detection

https://vsquad2022.aliqureshi.info/index.html •https://www.l2ti.univ-paris13.fr/VSQuad/



